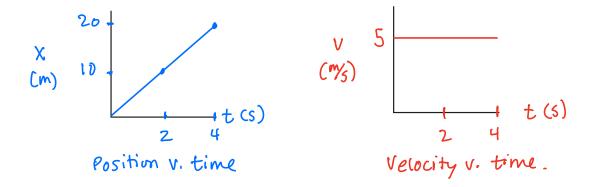
A new way to look @ graphs.

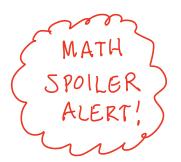
Let's imagine a car drives by at a constant speed of  $S^{m/s}$ . It would be easy to calculate now far The car went in 2 seconds or in 4 seconds, or any amount of time. We would simply Say  $d = \nabla t$ So in 2 seconds: d = (5)(2) = 10 m

in 4 seconds: d = (5)(4) = 20 m

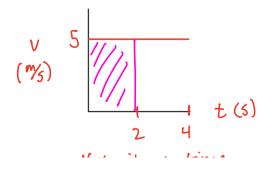
we will also make graphs of Position us. time and of velocity us. time as shown below:



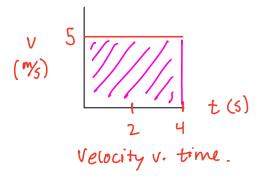
You already know that the <u>slope</u> of the position graph is the velocity. So the red velocity graph is the slope of the blue position graph.



The fundamental idea of calculus is that if quantity A is the <u>slope</u> of the graph of quantity B, then quantity B is the area under the graph of quantity A.



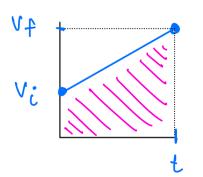
Notice that the pink rectangle has a "height" of 5 m/s and a "base" of 2 S. So its area is  $(5 \frac{m}{s})(2 s) = 10 m$ . Heg! That was the first calculation at the start of This document!



Now this one has a height of 5 m/s and a base of 4s. So its area is (5 m/s)(4s) = 20m. (which was the second calculation)

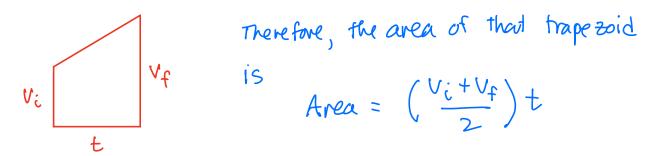
This means that the area under a velocity graph tells you the change in your position. This is the even if the velocity is not constant. Differential calculus will teach you how to find the slopes of almost any function and integral calculus will teach you how to find the area under most functions. It's really pretty cool. "

This idea is the key to seeing why we can say  $\overline{V} = \frac{V_i + V_f}{2}$  when the acceleration is constant.

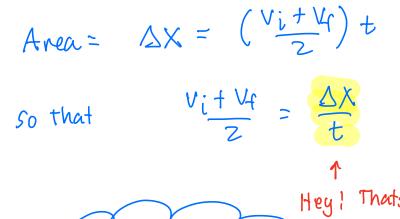


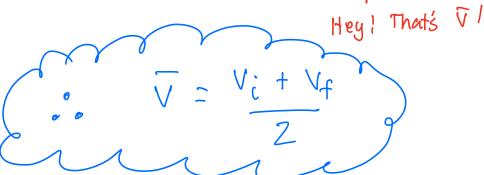
This graph shows a constant acceleration from on initial velocity of  $V_i$  to a final velocity  $V_f$ . The area under that graph is shaded pink and represents the change in position (SX) over that interval t.

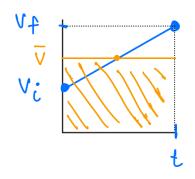
The velocity graph makes a trapezoid with a base of "t" and the two heights of " $V_i$ " and " $v_f$ ", shown below.



Since the area under the velocity graph is the change in position, we can say

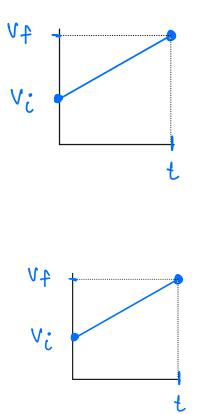


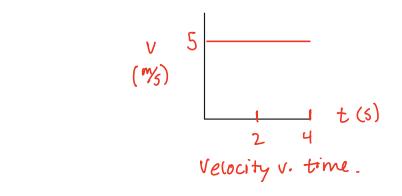


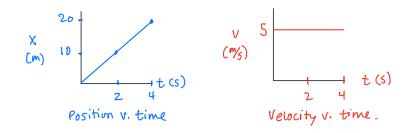


The average of  $V_i$  and  $V_f$  will be exactly in between  $V_i \notin V_f$ . Because the acceleration is constant,  $\nabla$  will "Cvt" the line connecting  $V_i \notin V_f$  in half, making a two little identical triangles.

In the two diagrams above, the area of the pink trapezoid is the same as the area of the orange rectangle







The velocity graph makes a trapezoid with a base of "t" and the two heights of " $V_i$ " and " $v_f$ ", shown below.

 $V_i$   $V_f$  is t  $V_f$   $V_f$   $Area = \left(\frac{V_i + V_f}{2}\right) t$ 

Since the area under the velocity graph is the change in position, we can say

Area = 
$$\Delta X = \left(\frac{v_i + v_f}{z}\right) t$$
  
so that  $\frac{v_i + v_f}{z} = \frac{\Delta X}{t}$   
Heg! That's  $\overline{v}$  /

